RELATIONS AND FUNCTIONS

KEY CONCEPT INVOLVED

- **Relations** Let A and B be two non-empty sets then every subset of $A \times B$ defines a relation from A to B and every relation from A to B is a subset of $A \times B$.
 - Let $R \subseteq A \times B$ and $(a, b) \in R$. then we say that a is related to b by the relation R as aRb. If $(a, b) \notin R$ as a R b.
- 2. **Domain and Range of a Relation** Let R be a relation from A to B, that is, let $R \subset A \times B$. then *Domain* $R = \{a : a \in A, (a, b) \in R \text{ for some } b \in B\}$ i.e. dom. R is the set of all the first elements of the ordered pairs which belong to R. *Range* $R = (b : b \in B, (a, b) \in R \text{ for some } a \in A\}$ i.e. range R is the set of all the second elements of the ordered pairs which belong to R. Thus Dom. $R \subset A$, Range $R \subset B$.
- 3. Inverse Relation Let $R \subset A \times B$ be a relation from A to B. Then inverse relation $R^{-1} \subset B \times A$ is defined by $R^{-1} \{(b, a) : (a, b) \in R\}$

It is clear that

- (i) $aRb = bR^{-1}a$
- (ii) dom. R^{-1} = range R and range R^{-1} = dom R.
- (iii) $(R^{-1})^{-1} = R$.
- **4.** Composition of Relation Let $R \subset A \times B$, $S \subset B \times C$ be two relations. Then composition of the relations R and S is denoted by $SoR \subset A \times C$ and is defined by $(a, c) \in (SoR)$ iff $b \in B$ such that $(a, b) \in R$, $(b, c) \in S$.
- **5.** Relations in a set let $A \neq \emptyset$ be a set and $R \subset A \times A$ i.e. R is a relation in the set A.
- **6.** Reflexive Relations R is a reflexive relation if $(a, a) \in R$, $\forall a \in R$ it should be noted that if for any $a \in A$ such that a \mathbb{R}' a. then R is not reflexive.
- 7. Symmetric Relation R is called symmetric relation on A if $(x, y) \in R \Rightarrow (y, x) \in R$.
 - i.e. if x is related to y, then y is also related to x.
 - It should be noted that R is symmetric iff $R^{-1} = R$.
- 8. Anti Symmetric Relations R is called an anti symmetric relation if $(a, b) \in R$ and $(b, a) \in R \Rightarrow a = b$. Thus if $a \ne b$ then a may be related to b or b may be related to a but never both.
- **9.** Transitive Relations R is called a transitive relation if $(a, b) \in R$ $(b, c) \in R \Rightarrow (a, c) \in R$
- 10. Identity Relations R is an identity relation if $(a, b) \in R$ iff a = b. i.e. every element of A is related to only itself and always identity relation is reflexive symmetric and transitive.
- 11. Equivalence Relations a relation R in a set A is called an equivalence relation if
 - (i) R is reflexive i.e. $(a, a) \in R \ \forall \ a \in A$
 - (ii) R is symmetric i.e. $(a, b) \in R \Rightarrow (b, a) \in R$
 - (iii) R is transitive i.e. $(a, b), (b, c) \in R \Rightarrow (a, c) \in R$.
- 12. Functions Suppose that to each element in a set A there is assigned, by some rule, an unique element of a set B. Such rules are called functions. If we let f denote these rules, then we write $f: A \to B$ as f is a function of A into B.
- 13. Equal Functions If f and g are functions defined on the same domain A and if f(a) = g(a) for every $a \in A$, then f = g.

- **14.** Constant Functions Let $f: A \to B$. If f(a) = b, a constant, for all $a \in A$, then f is called a constant function. Thus f is called a constant function if range f consists of only one element.
- 15. Identity Functions A function f is such that $A \rightarrow A$ is called an identity function if f(x) = x, $\forall x \in A$ it is denoted by I_A .
- **16.** One-One Functions (Injective) Let $f: A \to B$ then f is called a one-one function. If no two different elements in A have the same image i.e. different elements in A have different elements in B.

Denoted by symbol f is one-one if

$$f(a) = f(a') \Rightarrow a = a'$$

 $a \neq a' \Rightarrow f(a) \neq f(a')$

A mapping which is not one-one is called many one function.

- 17. Onto functions (Surjective) In the mapping $f: A \to B$, if every member of B appears as the image of at least one element of A, then we say "f is a function of A onto B or simply f is an onto functions" Thus f is onto iff f(A) = B
 - i.e. range = codomain

i.e.

A function which is not onto is called into function.

- **18.** Inverse of a function Let $f: A \to B$ and $b \in B$ then the inverse of b i.e. $f^{-1}(b)$ consists of those elements in A which are mapped onto b i.e. $f^{-1}(b) = \{x : x \in A, f(x) \in b\}$ $\therefore f^{-1}(b) \subset A, f^{-1}(b)$ may be a null set or a singleton.
- 19. Inverse Functions Let $f: A \to B$ be a one-one onto-function from A onto B. Then for each $b \in B$. $f^{-1}(b) \in A$ and is unique. So, $f^{-1}: B \to A$ is a function defined by $f^{-1}(b) = a$, iff f(a) = b.

Then f^{-1} is called the inverse function of f. If f has inverse function, f is also called invertible or non-singular.

Thus f is invertible (non-singular) iff it is one-one onto (bijective) function.

- **20.** Composition Functions Let $f: A \to B$ and $g: B \to C$, be two functions, Then composition of f and g denoted by gof: $A \to C$ is defined by (gof) (a) = $g \{f(a)\}$.
- 21. Binary Operation A binary operation * on a set A is a function *: $A \times A \rightarrow A$. We denote * (a, b) by a * b
- 22. Commutative Binary Operation A binary operation * on the set A is commutative if for every $a, b \in A$, a*b=b*a.
- 23. Associative Binary Operation A binary operation * on the set A is associative if (a * b) * c = a * (b * c).
- **24.** An Identity Element e for Binary Operation Let $*: A \times A \rightarrow A$ be a binary operation. There exists an element $e \in A$ such that $a*e=a=e*a \forall a \in A$, then e is called an identity element for Binary Operation *.
- **25.** Inverse of an Element a Let $*: A \times A \to A$ be a binary operation with identity element e in A. an element $a \in A$ is invertible w.r.t. binary operation *, if there exists an element b in A such that a * b = e = b * a. and b is called the inverse of a and is denoted by a^{-1} .

CONNECTING CONCEPTS

- 1. In general gof \neq fog.
- 2. $f: A \rightarrow B$, be one-one, onto then $f^{-1} \circ f = I$ and $f \circ f^{-1} = I$
- f^{-1} of = I_A and fof⁻¹ = I_B 3. $f: A \rightarrow B, g: B \rightarrow C, h: C \rightarrow D$ then (hog) of = ho (gof).
- **4.** $f: A \to B, g: B \to C$ be one-one and onto then gof: $A \to C$ is also one-one onto and $(gof)^{-1} = f^{-1} \circ g^{-1}$.
- 5. Let: $A \to B$, then I_B of = f and $fol_A = f$. It should be noted that fol_B is not defined since for $(fol_B)(x) = fo(\{I_B(x)\}) = f(x)$
 - $I_B(x)$ exist when $x \in B$ and f(x) exist when $x \in A$
- 6. $f: A \to B, g: B \to C$ are both one-one, then $gof: A \to C$ is also one-one it should be noted that for gof to be one-one f must be one-one.
- 7. If $f: A \to B$ $g: B \to C$ are both onto then gof must be onto. However, the converse is not true. But for gof to be onto g must be onto.

The domain of the functions

$$(f+g)(x) = f(x) + g(x)$$

$$(f-g)(x) = f(x) - g(x)$$

$$(fg)(x) = f(x)g(x)$$

is given by (dom. f) \cap (dom g) while domain of the function (f/g) (x) = $\frac{f(x)}{g(x)}$ is given by.

$$(dom f) \cap (dom. g) - \{x : g(x) = 0\}$$

- If O(A) = m, O(B) = n, then total number of mappings from A to B is n^m .
- 10. If A and B are finite sets and O(A) = m, O(B) = n, $m \le n$.

Then number of injection (one-one) from A to B is ${}^{n}P_{m} = \frac{n!}{(n-m)!}$

- 11. If $f: A \rightarrow B$ is injective (one-one), then $O(A) \le O(B)$.
- 12. If $f: A \rightarrow B$ is surjective (onto), then $O(A) \ge O(B)$.
- 13. If $f: A \rightarrow B$ is bijective (one-one onto), then O(A) = O(B).
- 14. Let $f: A \rightarrow B$ and O(A) = O(B), then f is one-one \Leftrightarrow it is onto.
- **15.** Let $f: A \to B$ and $X_1, X_2 \subseteq A$, then f is one-one iff $f(X_1 \cap X_2) = f(X_1) \cap f(X_2)$ **16.** Let $f: A \to B$ and $X \subseteq A, Y \subseteq B$, then in general $f^{-1}(f(x)) \subseteq X$, $f(f^{-1}(y)) \subseteq Y$ If f is one-one onto $f^{-1}(f(x)) = x$, $f(f^{-1}(y)) = Y$.

Class 12 Maths NCERT Solutions

| NCERT Solutions | Important Questions | NCERT Exemplar |
|--|---|--|
| Chapter 1 Relations and Functions | Relations and Functions | Chapter 1 Relations and Functions |
| Chapter 2 Inverse Trigonometric Functions | Concept of Relations and Functions | Chapter 2 Inverse Trigonometric Functions |
| Chapter 3 Matrices | Binary Operations | Chapter 3 Matrices |
| Chapter 4 Determinants | Inverse Trigonometric Functions | Chapter 4 Determinants |
| Chapter 5 Continuity and Differentiability | Matrices | Chapter 5 Continuity and Differentiability |
| Chapter 6 Application of Derivatives | Matrix and Operations of Matrices | Chapter 6 Application of Derivatives |
| Chapter 7 Integrals Ex 7.1 | Transpose of a Matrix and Symmetric Matrix | Chapter 7 Integrals |
| Integrals Class 12 Ex 7.2 | Inverse of a Matrix by Elementary Operations | Chapter 8 Applications of Integrals |
| Integrals Class 12 Ex 7.3 | Determinants | Chapter 9 Differential Equations |
| Integrals Class 12 Ex 7.4 | Expansion of Determinants | Chapter 10 Vector Algebra |
| Integrals Class 12 Ex 7.5 | Properties of Determinants | Chapter 11 Three Dimensional Geometry |
| | Inverse of a Matrix and Application of | Chapter 12 Linear |
| Integrals Class 12 Ex 7.6 | Determinants and Matrix | Programming |
| Integrals Class 12 Ex 7.7 | Continuity and Differentiability | Chapter 13 Probability |
| Integrals Class 12 Ex 7.8 | Continuity | |
| Integrals Class 12 Ex 7.9 | <u>Differentiability</u> | |
| Integrals Class 12 Ex 7.10 | Application of Derivatives | |
| Integrals Class 12 Ex 7.11 | Rate Measure Approximations and Increasing-Decreasing Functions | |
| Integrals Class 12 Miscellaneous Exercise | Tangents and Normals | |
| Chapter 8 Application of Integrals | Maxima and Minima | |
| Chapter 9 Differential Equations | Integrals | |
| Chapter 10 Vector Algebra | Types of Integrals | |
| Chapter 11 Three Dimensional Geometry | Differential Equation | |
| Chapter 12 Linear Programming | Formation of Differential Equations | |
| Chapter 13 Probability Ex | Solution of Different Types of Differential | |

| 13.1 | <u>Equations</u> | |
|-------------------------------|---|--|
| Probability Solutions Ex 13.2 | Vector Algebra | |
| Probability Solutions Ex 13.3 | Algebra of Vectors | |
| Probability Solutions Ex 13.4 | Dot and Cross Products of Two Vectors | |
| Probability Solutions Ex 13.5 | Three Dimensional Geometry | |
| | Direction Cosines and Lines | |
| | Plane | |
| | Linear Programming | |
| | Probability | |
| | Conditional Probability and Independent | |
| | Events | |
| | Baye's Theorem and Probability | |
| | <u>Distribution</u> | |

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| Chapter 1: Relations | <u>Chapter 12: Higher Order</u> <u>Derivatives</u> | Chapter 23 Algebra of Vectors |
|---|---|--|
| Chapter 2: Functions | Chapter 13: Derivative as a Rate Measurer | Chapter 24: Scalar Or Dot Product |
| Chapter 3: Binary Operations | Chapter 14: Differentials, Errors and Approximations | Chapter 25: Vector or Cross Product |
| Chapter 4: Inverse Trigonometric Functions | Chapter 15: Mean Value Theorems | Chapter 26: Scalar Triple Product |
| Chapter 5: Algebra of Matrices | Chapter 16: Tangents and Normals | Chapter 27: Direction Cosines and Direction Ratios |
| Chapter 6: Determinants | Chapter 17: Increasing and Decreasing Functions | Chapter 28 Straight line in space |
| Chapter 7: Adjoint and Inverse of a Matrix | Chapter 18: Maxima and Minima | Chapter 29: The plane |
| Chapter 8: Solution of Simultaneous Linear Equations | Chapter 19: Indefinite Integrals | Chapter 30: Linear programming |
| Chapter 9: Continuity | Chapter 20: Definite Integrals | Chapter 31: Probability |
| Chapter 10: Differentiability | Chapter 21: Areas of Bounded Regions | Chapter 32: Mean and variance of a random variable |
| Chapter 11: Differentiation | Chapter 22: Differential Equations | Chapter 33: Binomial Distribution |

JEE Main Maths Chapter wise Previous Year Questions

- 1. Relations, Functions and Reasoning
- 2. Complex Numbers
- 3. Quadratic Equations And Expressions
- 4. Matrices, Determinatnts and Solutions of Linear Equations
- 5. Permutations and Combinations
- 6. Binomial Theorem and Mathematical Induction
- 7. Sequences and Series
- 8. Limits, Continuity, Differentiability and Differentiation
- 9. Applications of Derivatives
- 10. Indefinite and Definite Integrals
- 11. Differential Equations and Areas
- 12. Cartesian System and Straight Lines
- 13. Circles and System of Circles
- 14. Conic Sections
- 15. Three Dimensional Geometry
- 16. <u>Vectors</u>
- 17. Statistics and Probability
- 18. Trignometry
- 19. Miscellaneous

NCERT Solutions for Class 12

- NCERT Solutions for Class 12 Maths
- NCERT Solutions for Class 12 Physics
- NCERT Solutions for Class 12 Chemistry
- NCERT Solutions for Class 12 Biology
- NCERT Solutions for Class 12 English
- NCERT Solutions for Class 12 English Vistas
- NCERT Solutions for Class 12 English Flamingo
- NCERT Solutions for Class 12 Hindi
- NCERT Solutions for Class 12 Hindi Aroh (आरोह भाग 2)
- NCERT Solutions for Class 12 Hindi Vitan (वितान भाग 2)
- NCERT Solutions for Class 12 Business Studies
- NCERT Solutions for Class 12 Accountancy
- NCERT Solutions for Class 12 Psychology
- NCERT Solutions for Class 12 Sociology
- NCERT Solutions for Class 12 History
- NCERT Solutions for Class 12 Entrepreneurship
- NCERT Solutions for Class 12 Political Science
- NCERT Solutions for Class 12 Economics
- NCERT Solutions for Class 12 Macro Economics
- NCERT Solutions for Class 12 Micro Economics
- NCERT Solutions for Class 12 Computer Science (C++)
- NCERT Solutions for Class 12 Computer Science (Python)