## Standard Loci in the Argand Plane.

(1) If z is a variable point in the argand plane such that  $\arg(z) = \theta$ , then locus of z is a straight line (excluding origin) through the origin inclined at an angle  $\theta$  with x-axis.

(2) If z is a variable point and  $z_1$  is a fixed point in the argand plane such that  $\arg(z - z_1) = \theta$ , then locus of z is a straight line passing through the point representing  $z_1$  and inclined at an angle  $\theta$  with x-axis. Note that the point  $z_1$  is excluded from the locus.

(3) If z is a variable point and  $z_1, z_2$  are two fixed points in the argand plane, then

(i)  $|z - z_1| \neq |z - z_2|$ Locus of z is the perpendicular bisector of  $\Rightarrow$ the line segment joining  $z_1$  and  $z_2$ (ii)  $|z - z_1| + |z - z_2| = \text{constant} (\neq |z_1 - z_2|)$ Locus of z is an ellipse  $\Rightarrow$ (iii)  $|z - z_1| + |z - z_2| \neq |z_1 - z_2|$ Locus of z is the line segment joining  $\Rightarrow$  $z_1$  and  $z_2$ (iv)  $|z - z_1| - |z - z_2| \neq |z_1 - |z_2|$ Locus of z is a straight line joining  $z_1$  and  $\Rightarrow$  $z_2$  but z does not lie between  $z_1$  and  $z_2$ . (v)  $|z - z_1| - |z - z_2| = \text{constant} \quad (\neq z_1 - z_2)$  $\Rightarrow$ Locus of z is a hyperbola. (vi)  $|z-z_1|^2 + |z-z_2|^2 = |z_1-z_2|$ Locus of z is a circle with  $z_1$  and  $z_2$  as the  $\Rightarrow$ extremities of diameter. (vii)  $|z - z_1| = k |z - z_2| k \neq 1$ Locus of z is a circle.  $\Rightarrow$ (viii)  $\arg\left(\frac{z-z_1}{z-z_2}\right) = \alpha$  (fixed) Locus of z is a segment of circle.  $\Rightarrow$ 

(ix) 
$$\arg\left(\frac{z-z_1}{z-z_2}\right) = \pm \pi/2$$
  $\Rightarrow$  Locus of z is a circle with  $z_1$  and  $z_2$  as the

vertices of diameter.

(x) 
$$\arg\left(\frac{z-z_1}{z-z_2}\right) = 0$$
 or  $\pi \implies \text{Locus z is a straight line passing through } z_1$   
and  $z_2$ .

(xi) The equation of the line joining complex numbers  $z_1$  and  $z_2$  is given by  $\frac{z-z_1}{z_2-z_1} = \frac{\overline{z}-\overline{z}_1}{\overline{z}_2-\overline{z}_1}$  or

 $\begin{vmatrix} z & \overline{z} & 1 \\ z_1 & \overline{z}_1 & 1 \\ z_2 & \overline{z}_2 & 1 \end{vmatrix} = 0$