

Special Types of Matrices.

(1) Symmetric and skew-symmetric matrix

(i) **Symmetric matrix:** A square matrix $A = [a_{ij}]$ is called symmetric matrix if $a_{ij} = a_{ji}$ for all i, j or $A^T = A$

Example:
$$\begin{bmatrix} a & h & g \\ h & b & f \\ g & f & c \end{bmatrix}$$

Note: Every unit matrix and square zero matrix are symmetric matrices.

□ Maximum number of different elements in a symmetric matrix is $\frac{n(n+1)}{2}$

(ii) **Skew-symmetric matrix:** A square matrix $A = [a_{ij}]$ is called skew-symmetric matrix if $a_{ij} = -a_{ji}$ for all i, j

or $A^T = -A$. Example:
$$\begin{bmatrix} 0 & h & g \\ -h & 0 & f \\ -g & -f & 0 \end{bmatrix}$$

Note: All principal diagonal elements of a skew-symmetric matrix are always zero because for any diagonal element. $a_{ij} = -a_{ij} \Rightarrow a_{ij} = 0$

□ Trace of a skew symmetric matrix is always 0.

Properties of symmetric and skew-symmetric matrices:

(i) If A is a square matrix, then $A + A^T, AA^T, A^T A$ are symmetric matrices, while $A - A^T$ is skew-symmetric matrix.

(ii) If A is a symmetric matrix, then $-A, KA, A^T, A^n, A^{-1}, B^T AB$ are also symmetric matrices, where $n \in \mathbb{N}$, $K \in \mathbb{R}$ and B is a square matrix of order that of A

(iii) If A is a skew-symmetric matrix, then

(a) A^{2n} is a symmetric matrix for $n \in \mathbb{N}$,

(b) A^{2n+1} is a skew-symmetric matrix for $n \in \mathbb{N}$,

(c) kA is also skew-symmetric matrix, where $k \in \mathbb{R}$,

(d) $B^T A B$ is also skew-symmetric matrix where B is a square matrix of order that of A .

(iv) If A, B are two symmetric matrices, then

(a) $A \pm B, AB + BA$ are also symmetric matrices,

(b) $AB - BA$ is a skew-symmetric matrix,

(c) AB is a symmetric matrix, when $AB = BA$.

(v) If A, B are two skew-symmetric matrices, then

(a) $A \pm B, AB - BA$ are skew-symmetric matrices,

(b) $AB + BA$ is a symmetric matrix.

(vi) If A a skew-symmetric matrix and C is a column matrix, then $C^T A C$ is a zero matrix.

(vii) Every square matrix A can uniquely be expressed as sum of a symmetric and skew-symmetric matrix *i.e.*

$$A = \left[\frac{1}{2}(A + A^T) \right] + \left[\frac{1}{2}(A - A^T) \right].$$

(2) **Singular and Non-singular matrix:** Any square matrix A is said to be non-singular if $|A| \neq 0$, and a square matrix A is said to be singular if $|A| = 0$. Here $|A|$ (or $\det(A)$ or simply $\det |A|$) means corresponding determinant of square matrix A .

Example: $A = \begin{bmatrix} 2 & 3 \\ 4 & 5 \end{bmatrix}$ then $|A| = \begin{vmatrix} 2 & 3 \\ 4 & 5 \end{vmatrix} = 10 - 12 = -2 \Rightarrow A$ is a non-singular matrix.

(3) **Hermitian and skew-Hermitian matrix:** A square matrix $A = [a_{ij}]$ is said to be hermitian

matrix if $a_{ij} = \bar{a}_{ji} \forall i, j$ *i.e.* $A = A^{\theta}$. *Example:* $\begin{bmatrix} a & b + ic \\ b - ic & d \end{bmatrix}, \begin{bmatrix} 3 & 3 - 4i & 5 + 2i \\ 3 + 4i & 5 & -2 + i \\ 5 - 2i & -2 - i & 2 \end{bmatrix}$ are

Hermitian matrices.

Note: If A is a Hermitian matrix then $a_{ii} = \bar{a}_{ii} \Rightarrow a_{ii}$ is real $\forall i$, thus every diagonal element of a Hermitian matrix must be real.

□ A Hermitian matrix over the set of real numbers is actually a real symmetric matrix and a square matrix, $A=[a_{ij}]$ is said to be a skew-Hermitian if $a_{ij} = -\bar{a}_{ji}, \forall i, j$. i.e. $A^{\theta} = -A$.

Example: $\begin{bmatrix} 0 & -2+i \\ 2-i & 0 \end{bmatrix}, \begin{bmatrix} 3i & -3+2i & -1-i \\ 3+2i & -2i & -2-4i \\ 1-i & 2-4i & 0 \end{bmatrix}$ are skew-Hermitian matrices.

□ If A is a skew-Hermitian matrix, then $a_{ii} = -\bar{a}_{ii} \Rightarrow a_{ii} + \bar{a}_{ii} = 0$ i.e. a_{ii} must be purely imaginary or zero.

□ A skew-Hermitian matrix over the set of real numbers is actually a real skew-symmetric matrix.

(4) **Orthogonal matrix:** A square matrix A is called orthogonal if $AA^T = I = A^T A$ i.e. if $A^{-1} = A^T$

Example: $A = \begin{bmatrix} \cos \alpha & -\sin \alpha \\ -\sin \alpha & \cos \alpha \end{bmatrix}$ is orthogonal because $A^{-1} = \begin{bmatrix} \cos \alpha & \sin \alpha \\ -\sin \alpha & \cos \alpha \end{bmatrix} = A^T$

In fact every unit matrix is orthogonal.

(5) **Idempotent matrix:** A square matrix A is called an idempotent matrix if $A^2 = A$.

Example: $\begin{bmatrix} 1/2 & 1/2 \\ 1/2 & 1/2 \end{bmatrix}$ is an idempotent matrix, because $A^2 = \begin{bmatrix} 1/4+1/4 & 1/4+1/4 \\ 1/4+1/4 & 1/4+1/4 \end{bmatrix} = \begin{bmatrix} 1/2 & 1/2 \\ 1/2 & 1/2 \end{bmatrix} = A$.

Also, $A = \begin{bmatrix} 1 & 0 \\ 0 & 0 \end{bmatrix}$ and $B = \begin{bmatrix} 0 & 0 \\ 0 & 1 \end{bmatrix}$ are idempotent matrices because $A^2 = A$ and $B^2 = B$.

In fact every unit matrix is idempotent.

(6) **Involutory matrix:** A square matrix A is called an involutory matrix if $A^2 = I$ or $A^{-1} = A$

Example: $A = \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix}$ is an involutory matrix because $A^2 = \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} = I$

In fact every unit matrix is involutory.

(7) **Nilpotent matrix:** A square matrix A is called a nilpotent matrix if there exists a $p \in \mathbb{N}$ such that $A^p = 0$

Example: $A = \begin{bmatrix} 0 & 0 \\ 1 & 0 \end{bmatrix}$ is a nilpotent matrix because $A^2 = \begin{bmatrix} 0 & 0 \\ 0 & 0 \end{bmatrix} = 0$ (Here $P = 2$)

(8) **Unitary matrix:** A square matrix is said to be unitary, if $\bar{A}' A = I$ since $|\bar{A}'| = |A|$ and $|\bar{A}' A| = |\bar{A}'| |A|$ therefore if $\bar{A}' A = I$, we have $|\bar{A}'| |A| = 1$

Thus the determinant of unitary matrix is of unit modulus. For a matrix to be unitary it must be non-singular.

Hence $\bar{A}' A = I \Rightarrow A \bar{A}' = I$

(9) **Periodic matrix:** A matrix A will be called a periodic matrix if $A^{k+1} = A$ where k is a positive integer. If, however k is the least positive integer for which $A^{k+1} = A$, then k is said to be the period of A .

(10) **Differentiation of a matrix:** If $A = \begin{bmatrix} f(x) & g(x) \\ h(x) & l(x) \end{bmatrix}$ then $\frac{dA}{dx} = \begin{bmatrix} f'(x) & g'(x) \\ h'(x) & l'(x) \end{bmatrix}$ is a differentiation of matrix A .

Example: If $A = \begin{bmatrix} x^2 & \sin x \\ 2x & 2 \end{bmatrix}$ then $\frac{dA}{dx} = \begin{bmatrix} 2x & \cos x \\ 2 & 0 \end{bmatrix}$

(11) **Submatrix :** Let A be $m \times n$ matrix, then a matrix obtained by leaving some rows or columns or both, of A is called a sub matrix of A . *Example:* If $A' = \begin{bmatrix} 2 & 1 & 0 \\ 3 & 2 & 2 \\ 2 & 5 & 3 \end{bmatrix}$ and $\begin{bmatrix} 2 & 2 \\ 5 & 3 \end{bmatrix}$ are sub matrices of

matrix $A = \begin{bmatrix} 2 & 1 & 0 & -1 \\ 3 & 2 & 2 & 4 \\ 2 & 5 & 3 & 1 \end{bmatrix}$

(12) **Conjugate of a matrix:** The matrix obtained from any given matrix A containing complex number as its elements, on replacing its elements by the corresponding conjugate complex

numbers is called conjugate of A and is denoted by \bar{A} . *Example:* $A = \begin{bmatrix} 1+2i & 2-3i & 3+4i \\ 4-5i & 5+6i & 6-7i \\ 8 & 7+8i & 7 \end{bmatrix}$

then $\bar{A} = \begin{bmatrix} 1-2i & 2+3i & 3-4i \\ 4+5i & 5-6i & 6+7i \\ 8 & 7-8i & 7 \end{bmatrix}$

Properties of conjugates:

- (i) $\overline{(\bar{A})} = A$
- (ii) $\overline{(A+B)} = \bar{A} + \bar{B}$
- (iii) $\overline{(\alpha A)} = \bar{\alpha} \bar{A}$, α being any number
- (iv) $\overline{(AB)} = \bar{A} \bar{B}$, A and B being conformable for multiplication.

(13) **Transpose conjugate of a matrix:** The transpose of the conjugate of a matrix A is called transposed conjugate of A and is denoted by A^θ . The conjugate of the transpose of A is the same as the transpose of the conjugate of A . i.e. $\overline{(A')} = (\overline{A})' = A^\theta$.

If $A = [a_{ij}]_{m \times n}$ then $A^\theta = [b_{ji}]_{n \times m}$ where $b_{ji} = \overline{a_{ij}}$ i.e. the $(j, i)^{th}$ element of A^θ = the conjugate of $(i, j)^{th}$ element of A .

Example: If $A = \begin{bmatrix} 1 + 2i & 2 - 3i & 3 + 4i \\ 4 - 5i & 5 + 6i & 6 - 7i \\ 8 & 7 + 8i & 7 \end{bmatrix}$, then $A^\theta = \begin{bmatrix} 1 - 2i & 4 + 5i & 8 \\ 2 + 3i & 5 - 6i & 7 - 8i \\ 3 - 4i & 6 + 7i & 7 \end{bmatrix}$

Properties of transpose conjugate

- (i) $(A^\theta)^\theta = A$
- (ii) $(A + B)^\theta = A^\theta + B^\theta$
- (iii) $(kA)^\theta = \overline{k}A^\theta$, k being any number
- (iv) $(AB)^\theta = B^\theta A^\theta$