## Important Facts and Formulae.

(1) When a body is suspended from two light springs separately. The time period of vertical oscillations are T1 and T2 respectively.

$$T_1 = 2\pi \sqrt{\frac{m}{k_1}}$$
  $k_1 = \frac{4\pi^2 m}{T_1^2}$  and  $T_2 = 2\pi \sqrt{\frac{m}{k_2}}$   $k_2 = \frac{4\pi^2 m}{T_2^2}$ 

When these two springs are connected in series and the same mass m is attached at lower end

and then for series combination  $\frac{1}{k} = \frac{1}{k_1} + \frac{1}{k_2}$ 

By substituting the values of 
$$k_1, k_2 \frac{T^2}{4\pi^2 m} = \frac{T_1^2}{4\pi^2 m} + \frac{T_2^2}{4\pi^2 m}$$

Time period of the system  $T = \sqrt{T_1^2 + T_2^2}$ 

When these two springs are connected in parallel and the same mass m is attached at lower end and then for parallel combination  $k = k_1 + k_2$ 

$$\frac{4\pi^2 m}{T^2} = \frac{4\pi^2 m}{T_1^2} + \frac{4\pi^2 m}{T_2^2}$$

By substituting the values of  $k_1, k_2$ 

$$T = \frac{T_1 T_2}{\sqrt{T_1^2 + T_2^2}}$$

Time period of the system

(2) The pendulum clock runs slow due to increase in its time period whereas it becomes fast due to decrease in time period.

(3) If infinite spring with force constant  $^{k, 2k, 4k, 8k}$  respectively are connected in series. The effective force constant of the spring will be  $^{k/2}$ .

(4) If  $y_1 = a \sin \omega t$  and  $y_2 = b \cos \omega t$  are two S.H.M. then by the superimposition of these two S.H.M. we get

$$\vec{y} = \vec{y}_1 + \vec{y}_2$$

$$y = a \sin \omega t + b \cos \omega t$$

$$y = A \sin(\omega t + \phi)$$
This is also the equation of S.H.M.

Where  $A = \sqrt{a^2 + b^2}$  and  $\phi = \tan^{-1}(b/a)$ 

(5) If a particle performs S.H.M. whose velocity is  $v_1$  at a  $x_1$  distance from mean position and velocity  $v_2$  at distance  $x_2$ 

$$\omega = \sqrt{\frac{v_1^2 - v_2^2}{x_2^2 - x_1^2}}, \quad T = 2\pi \sqrt{\frac{x_2^2 - x_1^2}{v_1^2 - v_2^2}} a = \sqrt{\frac{v_1^2 x_2^2 - v_2^2 x_1^2}{v_1^2 - v_2^2}};$$
$$v_{\text{max}} = \sqrt{\frac{v_1^2 x_2^2 - v_2^2 x_1^2}{x_2^2 - x_1^2}}$$